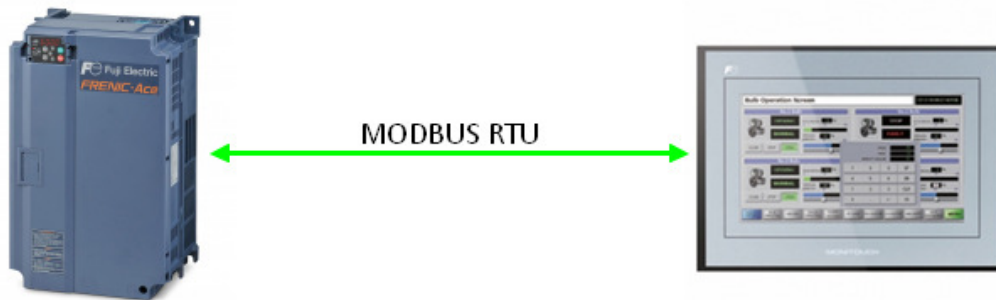


TECHNICAL INFORMATION	TI-TS-0002v100EN
REPLACEMENT INFO FOR OLD MODELS to TS2000	

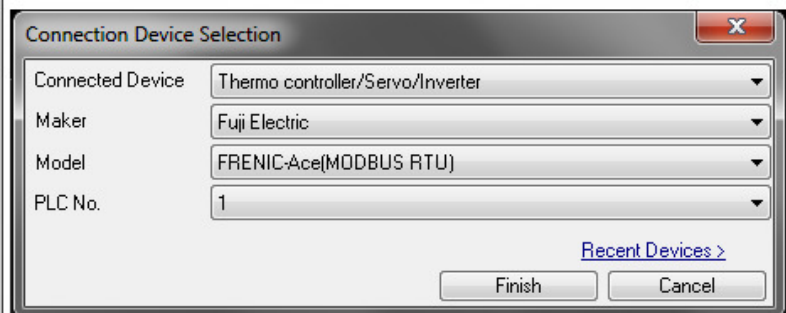
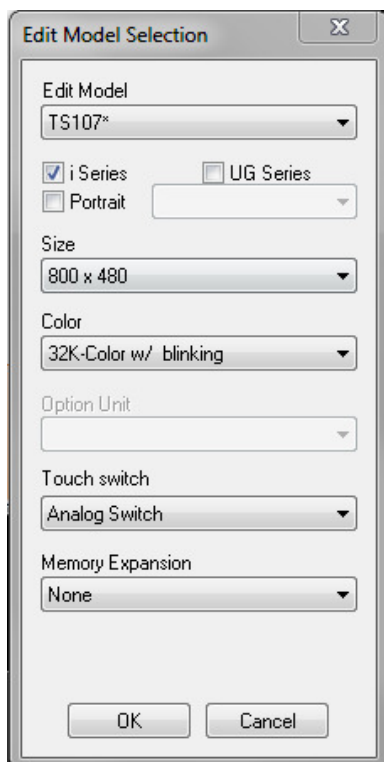
Type	TS
Software version	All versions
Required options	Not required
Use	Fuji technical staff
Date	20/11/2018
Version	1.0.0
Author	XXXXXXXXXX
Revised	XXXXXXXXXX
Approved	XXXXXXXXXX
Languages	English

TECHNOSHOT and Frenic ACE (MODBUS RTU)

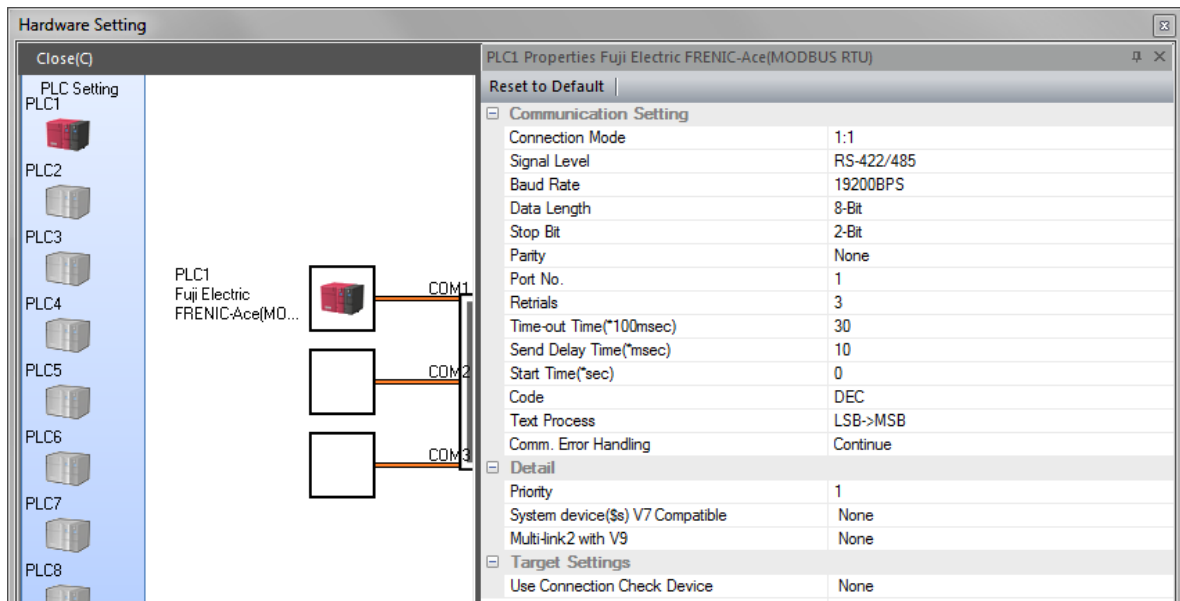
How to communicate a TS panel with a inverter Frenic ACE through RS485 Modbus RTU.



- 1- Ceate a screen program with V-SFT6, select a TS panel and select FRENIC-ACE Modbus RTU as a communication driver.



2- Set the communication parameters, these parameters must match with the inverter parameters.



3- Set the following parameters on the Frenic-ACE inverter.

Function Code	Item	Setting	Example															
y01	Station address	1 to 31	1															
y04	Baud rate	1: 4800 bps 2: 9600 bps 3: 19200 bps 4: 38400 bps	3															
y06	Parity bit	0: None 1: Even 2: Odd 3: None	0															
y07	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y06, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y06, "1 bit" is set for stop bit.	-															
y10	Communication protocol*1	0: Modbus RTU 1: SX (loader) protocol 2: FGI-bus	0															
y11	Station address	1 to 31	1															
y14	Baud rate	1: 4800 bps 2: 9600 bps 3: 19200 bps 4: 38400 bps	3															
y16	Parity bit	0: None 1: Even 2: Odd 3: None	0															
y17	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y16, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y16, "1 bit" is set for stop bit.	-															
y20	Communication protocol*1	0: Modbus RTU 2: FGI-bus	0															
y98	Bus function	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table>		Frequency	Operation Command	0	Function code H30	Function code H30	1	Commanded from the fieldbus	Function code H30	2	Function code H30	Commanded from the fieldbus	3	Commanded from the fieldbus	Commanded from the fieldbus	0
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Function Code	Item	Setting	Example																														
y99	Support link function	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30, y98</td> <td>Function code H30, y98</td> </tr> <tr> <td>1</td> <td>Commanded from the loader</td> <td>Function code H30, y98</td> </tr> <tr> <td>2</td> <td>Function code H30, y98</td> <td>Commanded from the loader</td> </tr> <tr> <td>3</td> <td>Commanded from the loader</td> <td>Commanded from the loader</td> </tr> </tbody> </table>		Frequency	Operation Command	0	Function code H30, y98	Function code H30, y98	1	Commanded from the loader	Function code H30, y98	2	Function code H30, y98	Commanded from the loader	3	Commanded from the loader	Commanded from the loader	0															
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3	Commanded from the loader	Commanded from the loader																															
H30	Link function *2	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Inverter</td> <td>Inverter</td> </tr> <tr> <td>1</td> <td>RS-485 communication</td> <td>Inverter</td> </tr> <tr> <td>2</td> <td>Inverter</td> <td>RS-485 communication</td> </tr> <tr> <td>3</td> <td>RS-485 communication</td> <td>RS-485 communication</td> </tr> <tr> <td>4</td> <td>RS-485 communication (control circuit)</td> <td>Inverter</td> </tr> <tr> <td>5</td> <td>RS-485 communication (control circuit)</td> <td>RS-485 communication</td> </tr> <tr> <td>6</td> <td>Inverter</td> <td>RS-485 communication (control circuit)</td> </tr> <tr> <td>7</td> <td>RS-485 communication</td> <td>RS-485 communication (control circuit)</td> </tr> <tr> <td>8</td> <td>RS-485 communication (control circuit)</td> <td>RS-485 communication (control circuit)</td> </tr> </tbody> </table>		Frequency	Operation Command	0	Inverter	Inverter	1	RS-485 communication	Inverter	2	Inverter	RS-485 communication	3	RS-485 communication	RS-485 communication	4	RS-485 communication (control circuit)	Inverter	5	RS-485 communication (control circuit)	RS-485 communication	6	Inverter	RS-485 communication (control circuit)	7	RS-485 communication	RS-485 communication (control circuit)	8	RS-485 communication (control circuit)	RS-485 communication (control circuit)	3
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3	RS-485 communication	RS-485 communication																															
4	RS-485 communication (control circuit)	Inverter																															
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- *1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the TS.
- *2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the TS.
When making the frequency and operation command settings on the TS connected to the connector for the touch panel, specify "3" for function code H30. When making those settings on the TS connected to the terminal block on control circuit, specify "8" for function code H30.
- *3 The communication parameter (data length) is fixed to 8 bits.

4- Connection diagram. (Make sure to put on TS, DIP switches 2 and 3 to ON)

Wiring diagram 10 - COM1

